

9.2 Dot product (briefly)

ex: $\vec{v} = \langle 2, 5 \rangle$ $\vec{w} = \langle 4, 7 \rangle$

$$\vec{v} \cdot \vec{w} = (2)(4) + (5)(7) \\ = 8 + 35 = 43$$

ex: $\vec{v} = \langle 2, 5 \rangle$ $\vec{u} = \langle 5, -2 \rangle$

$$\vec{v} \cdot \vec{u} = (2)(5) + (5)(-2) = 10 - 10 = 0$$

ex: $\vec{v} = \langle 2, 5 \rangle$ $\vec{j} = \langle 0, 1 \rangle$

$$\vec{v} \cdot \vec{j} = (2)(0) + (5)(1) = 5$$

Defn: $\vec{u} = \langle a_1, b_1 \rangle$ and $\vec{v} = \langle a_2, b_2 \rangle$

define the dot product of $\vec{u}$ and $\vec{v}$

$$\boxed{\vec{u} \cdot \vec{v} = a_1 a_2 + b_1 b_2} \quad \leftarrow \text{a number not a vector.}$$

Facts: 1. $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$

2. $(a \vec{u}) \cdot \vec{v} = \vec{u} \cdot a \vec{v} = a(\vec{u} \cdot \vec{v})$

3. $(\vec{u} + \vec{v}) \cdot \vec{w} = \vec{u} \cdot \vec{w} + \vec{v} \cdot \vec{w}$

4. $\vec{u} \cdot \vec{u} = |\vec{u}|^2$

ex: $\vec{u} = \langle 3, 4 \rangle$ $\vec{u} \cdot \vec{u} = (3)(3) + (4)(4) = 9 + 16 = 25$

$$|\vec{u}| = \sqrt{3^2 + 4^2} = \sqrt{25} \quad \text{so } |\vec{u}|^2 = 25 = \vec{u} \cdot \vec{u}$$

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Since
ex. $\vec{i} = \langle 1, 0 \rangle$ $\vec{j} = \langle 0, 1 \rangle$

$$\vec{i} \cdot \vec{i} = 1 \quad \vec{j} \cdot \vec{j} = 1 \quad \vec{i} \cdot \vec{j} = 0$$

We can the vector $\vec{i}$ and $\vec{j}$ form an
orthonormal system because

(1) $\vec{i} \cdot \vec{j} = 0$ says $\vec{i}$ and $\vec{j}$ are orthogonal

(2) $|\vec{i}| = 1$ and $|\vec{j}| = 1$ ^{both} have length 1.

Fact: ~~Geometric~~

Remark: These three facts, together with the
distributive property completely determine
the dot product.

ex. $\vec{u} = 2\vec{i} + 5\vec{j}$ $\vec{v} = 3\vec{i} + 7\vec{j}$

$$\vec{u} \cdot \vec{v} = (2\vec{i} + 5\vec{j}) \cdot (3\vec{i} + 7\vec{j})$$

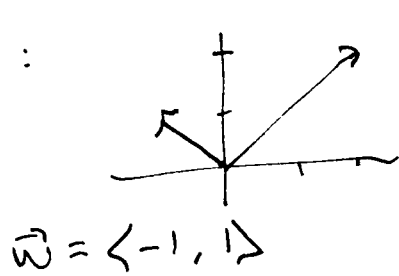
$$= (2)(3) \vec{i} \cdot \vec{i} + (2)(7) \vec{i} \cdot \vec{j} + (5)(3) \vec{j} \cdot \vec{i} + (5)(7) \vec{j} \cdot \vec{j}$$

$$= (2)(3) + (5)(7) = 6 + 35 = 41$$

Fact [Geometric interpretation]

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta, \text{ where } \theta = \text{angle between } \vec{u} \text{ and } \vec{v}$$

the idea of proof: Based on the Law of Cosines.

ex :

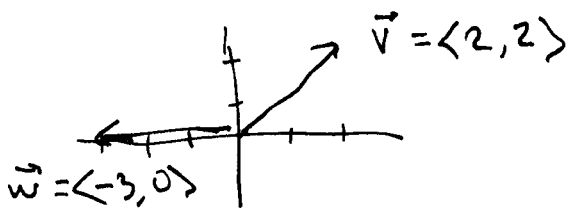
$$\vec{v} \cdot \vec{w} = (2)(-1) + (2)(1) = 0$$

Also

$$|\vec{v}| |\vec{w}| \cos \theta = (2\sqrt{2})(\sqrt{2}) \cos 90^\circ = 0$$

Remark: If $|\vec{u}| \neq 0$ and $|\vec{v}| \neq 0$

$$\cos \theta = \frac{\vec{u} \cdot \vec{v}}{|\vec{u}| |\vec{v}|}$$

ex: Find the angle between $\vec{v} = \langle 2, 2 \rangle$
and $\vec{w} = \langle -3, 0 \rangle$ 

$$|\vec{v}| = \sqrt{2^2 + 2^2} = 2\sqrt{2}$$

$$|\vec{w}| = \sqrt{(-3)^2 + 0^2} = 3$$

$$\begin{aligned} \vec{v} \cdot \vec{w} &= (2)(-3) + (2)(0) \\ &= -6 \end{aligned}$$

$$\cos \theta = \frac{\vec{v} \cdot \vec{w}}{|\vec{v}| |\vec{w}|} = \frac{-6}{(2\sqrt{2})(3)} = \frac{-6}{6\sqrt{2}} = \frac{-1}{\sqrt{2}} = \frac{-\sqrt{2}}{2}$$

$$\text{So } \theta = \cos^{-1}\left(\frac{-\sqrt{2}}{2}\right) = 135^\circ$$

Remark: (1) If $\vec{v} \cdot \vec{w} > 0$, then $\theta < 90^\circ$ (2) If $\vec{v} \cdot \vec{w} = 0$, then $\theta = 90^\circ$ (3) If $\vec{v} \cdot \vec{w} < 0$, then $\theta > 90^\circ$.Read the rest of the section to understand projections of vectors.

Brief review of 10.2

Solve

$$10.2 \quad 8) \quad \begin{cases} x + y - 3z = 8 \\ y - 3z = 5 \\ \boxed{z = -1} \end{cases}$$

we're ready
for back-
substitution.

$$y - 3(-1) = 5$$

$$y + 3 = 5 \Rightarrow \boxed{y = 2}$$

$$x + 2 - 3(-1) = 8$$

$$x + 5 = 8 \Rightarrow \boxed{x = 3}$$

$$\boxed{(x, y, z) = (3, 2, -1)}$$

19) Do Gaussian elimination on the system

$$\begin{array}{l} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \end{array} \left\{ \begin{array}{l} x + y + z = 4 \\ x + 3y + 3z = 10 \\ 2x + y - z = 3 \end{array} \right.$$

$$-1 \cdot \textcircled{1} : -x - y - z = -4$$

$$\textcircled{2} : \begin{array}{r} x + 3y + 3z = 10 \\ \hline 2y + 2z = 6 \end{array}$$

$$\textcircled{2'} \quad \text{so} \quad y + z = 3$$

Now take

$$\begin{array}{rcl}
 -2 \cdot (1) : & -2x & -2y - 2z = -8 \\
 (3) : & 2x & + y - z = 3 \\
 \hline
 & & -y - 3z = -5 \\
 (3') & \text{So} & y + 3z = 5
 \end{array}$$

New, equivalent system:

$$\begin{array}{l}
 (1) \\
 (2') \\
 (3')
 \end{array}
 \left\{
 \begin{array}{rcl}
 x & + & y + z = 4 \\
 & & y + z = 3 \\
 & & y + 3z = 5
 \end{array}
 \right.$$

$$\begin{array}{rcl}
 -1 \cdot (2') : & -y & - z = -3 \\
 (3'') : & y + 3z & = 5 \\
 \hline
 & 2z & = 2 \\
 (3'') & \text{So} & z = 1
 \end{array}$$

This system is equivalent to our original system of equations:

$$\begin{array}{l}
 (1) \\
 (2') \\
 (3'')
 \end{array}
 \left\{
 \begin{array}{rcl}
 x & + & y + z = 4 \\
 & & y + z = 3 \\
 & & z = 1
 \end{array}
 \right.$$

and we would be ready for back-substitution.

10.3 Gaussian Elimination using Matrices

Remark: The original system in §10.2 #19
can be represented by the "augmented matrix"

$$\begin{bmatrix} 1 & 1 & 1 & 4 \\ 1 & 3 & 3 & 10 \\ 2 & 1 & -1 & 3 \end{bmatrix} \quad \leftarrow \begin{array}{l} \text{a } 3 \times 4 \\ \text{matrix} \\ 3 \text{ rows} \\ 4 \text{ columns} \end{array}$$

We will do "elementary row operations" to
modify the matrix into "row equivalent matrix"

$$\begin{bmatrix} 1 & 1 & 1 & 4 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 1 & 1 \end{bmatrix} \quad \text{in "row-echelon form."}$$

This matrix then represents the system, equivalent to
the original system:

$$\begin{cases} x + y + z = 4 \\ \quad y + z = 3 \\ \quad \quad z = 1 \end{cases}$$

and then back-
substitute.

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Elementary Row Operations come in three flavors:

(1) Add a multiple of (a copy of) one row to another.

e.g. $-2R_1 + R_3 \rightarrow R_3$..

(2) Multiply a row by a (nonzero) number.

e.g. $\frac{1}{2} R_2$..

(3) Swap two rows. e.g. $R_1 \leftrightarrow R_3$..

ex. ^{10.3} #21)
$$\begin{cases} x + y + z = 2 \\ 2x - 3y + 2z = 4 \\ 4x + y - 3z = 1 \end{cases}$$

So the corresponding augmented matrix is:

T184: *row + (-2, Ans, 1, 2)

$$\begin{bmatrix} 1 & 1 & 1 & 2 \\ 2 & -3 & 2 & 4 \\ 4 & 1 & -3 & 1 \end{bmatrix}$$

$$-2R_1 + R_2 \rightarrow R_2 \begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & -5 & 0 & 0 \\ 4 & 1 & -3 & 1 \end{bmatrix}$$

*row + (-4, Ans, 1, 3)

$$-4R_1 + R_3 \rightarrow R_3 \begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & -5 & 0 & 0 \\ 0 & -3 & -7 & -7 \end{bmatrix}$$

*row (-1/5, Ans, 2)

$$-\frac{1}{5}R_2 \begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & -3 & -7 & -7 \end{bmatrix}$$

$$3R_2 + R_3 \rightarrow R_3 \begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -7 & -7 \end{bmatrix}$$

$$-\frac{1}{7}R_3 \begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

*row + (3, Ans, 2, 3)

*row (-1/7, Ans, 3)

What the heck. Let's try for Reduced-row-echelon form.

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$$-1R_3 + R_1 \rightarrow R_1 \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$-1 \cdot R_2 + R_1 \rightarrow R_1 \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

we have just done
Gauss-Jordan
elimination

The underlying system of equations:

$$1x + 0y + 0z = 1$$

$$0x + 1y + 0z = 0$$

$$0x + 0y + 1z = 1$$

$$\text{OR} \begin{cases} x & = 1 \\ y & = 0 \\ z & = 1 \end{cases}$$

25)

$$\begin{bmatrix} 1 & 2 & -1 & 9 \\ 2 & 0 & -1 & -2 \\ 3 & 5 & 2 & 22 \end{bmatrix} \xrightarrow{\text{ref}} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

T184: $\text{rref}([A])$

$$x = -1$$

$$y = 5$$

$$z = 0$$

Remark: We have yet to see what happens in Gaussian elimination (or Gauss-Jordan elimination) when the system is dependent or is inconsistent.